

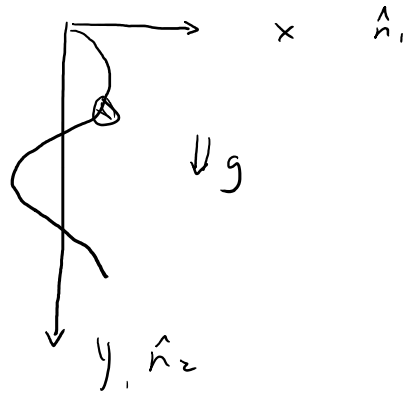
Ch. 4 Practice (1, 4) & Hw (5, 7)

Thursday, July 20, 2017 11:50 AM

Find EOM

4.1 $x = A \sin\left(\frac{2\pi y}{L}\right)$

$q = \{y\}$
 $\vec{r} = x \hat{n}_1 + y \hat{n}_2 = A \sin\left(\frac{2\pi y}{L}\right) \hat{n}_1 + y \hat{n}_2$
 $\dot{\vec{r}} = A \cos\left(\frac{2\pi y}{L}\right) \cdot \frac{2\pi}{L} \dot{y} \hat{n}_1 + \dot{y} \hat{n}_2$



$T = \frac{1}{2} m \dot{\vec{r}} \cdot \dot{\vec{r}}$
 $= \frac{1}{2} m \left(\left(\frac{2\pi A}{L}\right)^2 \cos^2\left(\frac{2\pi y}{L}\right) + 1 \right) \dot{y}^2$

$V = -mgy$

$q, = y:$

$2 \frac{\partial T}{\partial y} = \frac{\partial}{\partial y} \left(\frac{1}{2} m \dot{y}^2 \left(\left(\frac{2\pi A}{L}\right)^2 \cos^2\left(\frac{2\pi y}{L}\right) + 1 \right) \right)$

$\frac{\partial T}{\partial \dot{y}} = m \left(\frac{2\pi A}{L} \cos\left(\frac{2\pi y}{L}\right) \right) \dot{y}$

$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{y}} \right) = m \left(\text{temp} \right) \ddot{y}$

$\frac{\partial V}{\partial y} = -mg$

$Q_y = 0$

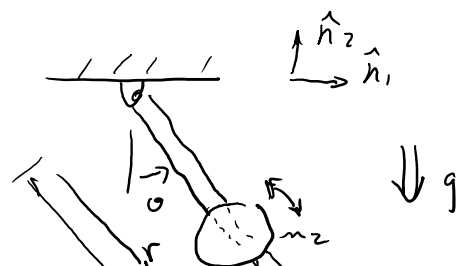
$m \left(\frac{2\pi A}{L} \cos\left(\frac{2\pi y}{L}\right) \right) \ddot{y} + m \dot{y}^2 \left(\frac{2\pi A}{L} \cos\left(\frac{2\pi y}{L}\right) \right) \sin\left(\frac{2\pi y}{L}\right) - mg = 0$

EOM.

4-4

$q = \{r, \theta\}^T$

$\frac{1}{2} m v^2 + \frac{1}{2} m v_z^2$



$$y = (1) \dots$$

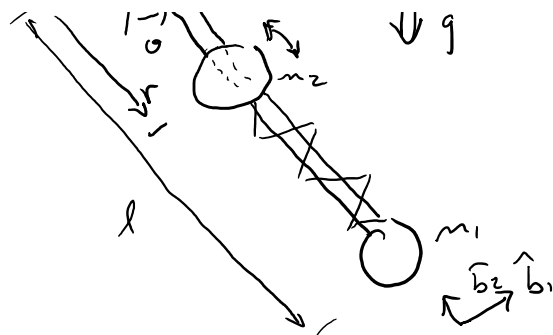
$$T = \frac{1}{2} M_1 v_1^2 + \frac{1}{2} M_2 v_2^2$$

$$\vec{r}_1 = -l \hat{b}_2; \quad \vec{v}_1 = l \dot{\theta} \hat{b}_1$$

$$\vec{r}_2 = -r \hat{b}_2; \quad \vec{v}_2 = -\dot{r} \hat{b}_2 + r \dot{\theta} \hat{b}_1$$

$$T = \frac{1}{2} M_1 l^2 \dot{\theta}^2 + \frac{1}{2} M_2 (\dot{r}^2 + r^2 \dot{\theta}^2)$$

$$V = -M_1 l c \theta - M_2 r c \theta + \frac{1}{2} k (l-r)^2 \leftarrow \text{assumes } 0 \text{ unstretched length.}$$



$$f = r:$$

$$\frac{\partial T}{\partial r} = M_2 \dot{\theta}^2$$

$$\frac{\partial T}{\partial \dot{r}} = M_2 \dot{\theta}$$

$$\frac{d}{dt} \frac{\partial T}{\partial \dot{r}} = M_2 \ddot{\theta}$$

$$\frac{\partial V}{\partial r} = -M_2 c \theta - k(l-r)$$

$$Q_r = 0$$

$$M_2 \ddot{\theta} - M_2 r \dot{\theta}^2 - M_2 c \theta - k(l-r) = 0$$

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$$f = \theta$$

$$\frac{\partial T}{\partial \theta} = 0$$

$$\frac{\partial T}{\partial \dot{\theta}} = M_1 (l^2 + r^2) \dot{\theta}$$

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{\theta}} \right) = M_1 (l^2 + r^2) \ddot{\theta} + 2M_1 \dot{\theta} r \dot{r}$$

$$\frac{\partial V}{\partial \theta} = +M_1 l s \theta + M_2 r s \theta$$

$$Q_\theta = 0$$

$$M_1 (l^2 + r^2) \ddot{\theta} + 2M_1 \dot{\theta} r \dot{r} + M_1 l s \theta + M_2 r s \theta = 0$$

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